DPCM, DM AND ADM

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OUTLINE

- Overview of PCM
- **DPCM**
- ► DM
- ► ADM

PCM

Pulse digital base band data transmission techniques are PCM, DPCM, DM and ADM.

- PCM stands for Pulse Code Modulation.
- In n- bit PCM, step size = $\Delta = \frac{V_{\text{max}} V_{\text{min}}}{2^n}$
- Where $2^{n} = no$. of quantization levels.
- The quantization noise power in PCM = $N_q = \frac{\Delta^2}{12}$
- In order to decrease the quantization error, either we have to increase the value of n or decrease the value of V_{max} - V_{min} .
- V_{max} - V_{min} is known as dynamic range of the input message signal.

DPCM

- Differential Pulse Code Modulation (DPCM) is the process of converting an analog to digital signal in which the difference between the successive samples are applied to the quantizer.
- Block diagram of DPCM transmitter is shown here.



DPCM RECEIVER



Why DPCM?

- Reduces the quantisation error without increasing the no. of bits of n.
- Dynamic range of the quantizer can be minimised.
- For the dynamic range, the difference between two successive samples are applied.
- Bit rate is same as PCM
- Bit rate: $R_b = \frac{n}{T_s}$
- Quantisation noise is reduced

DISADVANTAGE: Hardware complexity.

DM

□ It is used to reduce the bandwidth of the signal

- □ It has 1-bit encoder.
- □ It is always considered as 1-bit DPCM.



DM TRANSMITTER



DM RECEIVER



Transfer characteristics of Quantizer in DM in terms of step size \triangle +ve $-\Delta$ -ve

> In PCM, DPCM:- Rb=(1/Ts) * n

> In DM:- n=1

Rb=1/Ts = pulse rate

> At the receiver '1' is decoded as $+\triangle$ and '0' is decoded as $-\triangle$.

So, the input to the LPF increases or decreases in terms of . The signal reconstruction depends on the value of .

Types of DM errors:-

- **1. Slope overload error:**
- When the step size is very low; slope overload error occurs.

$$\frac{\Delta}{Ts} < \frac{d}{dt} \mathrm{m}(\mathrm{t})$$

2. Granular Noise Error:

• When the slope of reconstructed signal is high as compared to $\frac{d}{dt}m(t)$; then Granular noise occurs.

$$\frac{\Delta}{Ts} > \frac{d}{dt} m(t)$$

NOTE:

✓ When the slope of transmitted waveform and slope of reconstructed waveform are same; there will be no error.

$$\frac{\Delta}{Ts} = \frac{d}{dt}m(t)$$

Here; $\Delta = \text{Ts} \frac{d}{dt}m(t)$
$$\Delta = \frac{\text{Slope of the signal}}{\text{sampling rate}} = \frac{\frac{d}{dt}m(t)}{1/Ts}$$





• <u>CASE 2 :</u> • If m(t) = Amcos2 $\mathbf{\Pi} f_m t$ Am † -Am Slope: $\frac{d}{dt}m(t) = \frac{d}{dt}Amcos2\Pi f_m t = -Amsin2\Pi f_m t. 2\Pi f_m$ $\frac{d}{dt}m(t) = -\operatorname{Am}2\boldsymbol{\Pi}fm\sin 2\boldsymbol{\Pi}f_mt$ $\frac{d}{dt}m(t) = \text{Am}2\boldsymbol{\Pi}f_m$ max Am2∏fm

PROBLEMS

Q1. The i/p to the delta modulator is m(t)=5t and sampling rate is 5000 samples/sec. Determine the step size.

Ans-Here, m(t)=5t. So, dm(t)/dt=5.

Step size=5/5000=5mV.

Q2. The i/p to the delta modulator is $m(t)=5\cos 2\pi 1000t$ and the pulse rate is 56000 pulses/sec. Determine the step size.

Ans- Here A_m=5 V, f_m=1000, pulse rate=bit rate=sampling rate=56000. Step size= $\Delta = \frac{5 \times 2\pi \times 1000}{56000}$ V (volt).

ADM :

- \rightarrow Stands for adaptive delta modulation
- \rightarrow In ADM additional hardware is designed to provide variable step size .
- Thereby reducing slope overload effects without increasing the granular noise.



ADM TRANSMITTER



THANK YOU