

MODELLING and SIMILARITY

- The dimensional analysis what you are studying is used in modelling studies.
- You saw the Buckingham Π theorem.

- How will you do it practically?
 - Selection of variables is important. It requires good experience to decide which variable is important, etc.
 - Based on the requirement, the engineer can judge and suggest
 - ❖ That viscous flows can be neglected or not.
 - ❖ Temperature effects can be neglected or not.
 - ❖ Whether surface tension is important or not.
 - ❖ Gravitational force is important or not, etc.

 - Once the variables are selected, you need to perform analysis. Identify Π 's.
 - The experimenters will try to seek similarity between the model and the prototype designed.

- On any phenomena, the engineer may come up with a non-dimensional relation.
$$\Pi_1 = f(\Pi_1, \Pi_2, \Pi_3, \dots, \Pi_k)$$
- The flow conditions of a model test will be completely similar to the prototype, if all the dimensionless parameters of the model (say $\Pi_2, \Pi_3, \Pi_4, \dots, \Pi_k$) is same as the prototype.

i.e. You require

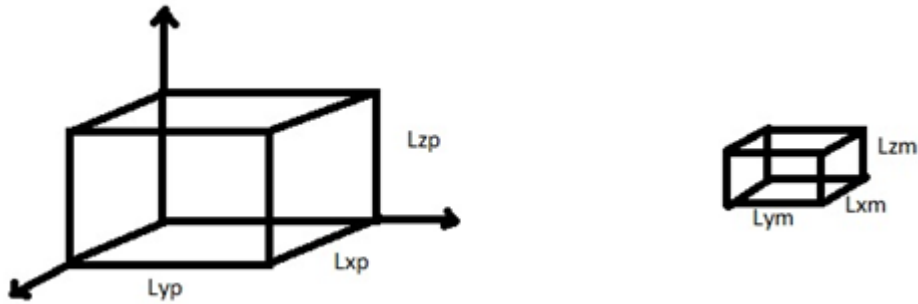
$$\Pi_{2m} = \Pi_{2p}; \quad \Pi_{3m} = \Pi_{3p}; \dots$$

- It is very difficult to achieve complete similarity between a model and a prototype.
- However, by compromising various features, you can have:
 - Geometric similarity between model and prototype
 - Kinematic similarity
 - Dynamic similarity
 - Thermal similarity

➤ **Geometric similarity**

If all the length dimensions [L] of the model and the prototype are having same linear scale ratio, the model and prototype is said to be geometrically similar.

For a body, if the dimensions in the x, y, z directions are L_{xp} , L_{yp} , L_{zp}
Then, if you have a miniature model of dimensions L_{xm} , L_{ym} , L_{zm} .



And if $\frac{L_{xm}}{L_{xp}} = \frac{L_{ym}}{L_{yp}} = \frac{L_{zm}}{L_{zp}} = \text{constant}$,

Then this model is **geometrically similar** to the prototype)

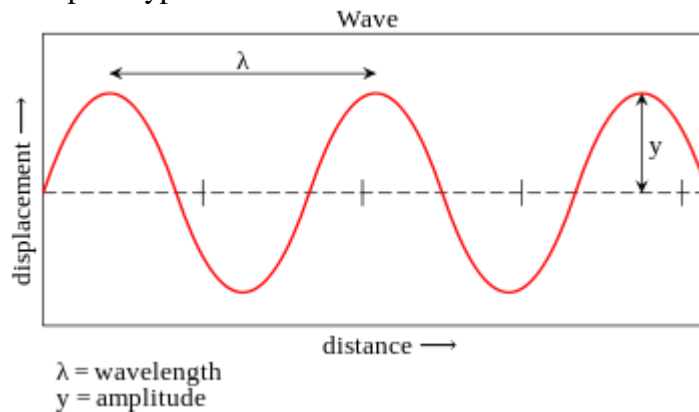
➤ You can visualise homologous points between the model and prototype.

➤ **Kinematic Similarity**

- If the model and prototype have same length scale ratio (i.e. geometric similarity) and in addition have same time scale ratio, then they are kinematically similar.
- For time scale equilibrium, you may require evidence of Reynolds Number and Mach Number, etc.
- For fluid flows you have seen that one can neglect or incorporate effects of viscosity (or friction).
- For a frictionless flow like free surface flow, the model and prototype can be made kinematically similar. (How???)
 - You have to provide the same Froude Number.

➤ Recall earlier, we had described Froude's Number as $Fr = \frac{U}{\sqrt{gL}}$

For example in a Wave Motion Modelling Studies:
The prototype wave:



(Source :[https://en.wikibooks.org/wiki/Alevel_Physics_\(Advancing_Physics\)/What_is_a_wave%3F](https://en.wikibooks.org/wiki/Alevel_Physics_(Advancing_Physics)/What_is_a_wave%3F))

- In the wave modelling studies, the actual or prototype wave may be large and its wave length can be large.
- A model of the wave can be developed in laboratory by providing kinematically similar conditions.
- In kinematic similarity, the Froude number have to be equal.

$$\text{i.e. } Fr_m = \frac{V_m}{\sqrt{gL_m}} = \frac{V_p}{\sqrt{gL_p}} = Fr_p$$

$$\text{or } \frac{V_m^2}{gL_m} = \frac{V_p^2}{gL_p}$$

$$\text{or } \frac{V_m}{V_p} = \sqrt{\frac{L_m}{L_p}}$$

$$\text{If } \frac{L_m}{L_p} = \alpha, \text{ Then } \frac{V_m}{V_p} = \sqrt{\alpha}$$

$$\frac{t_m}{t_p} = \frac{L_m/V_m}{L_p/V_p} = \sqrt{\alpha}$$

- If viscosity, and surface tension, etc. play important role in flow of the fluid, then kinematic similarity may not be sufficient. You may have to go for dynamic similarity.

Dynamic Similarity:

- The model and the prototype are dynamically similar, if they have same length scale ratio, same time scale ratio and same force ratio.
- From Newton's law, for any fluid particle-the sum of pressure force, gravity force, and friction force is equal to the net force or inertial force.

$$\begin{array}{ccccccc} \vec{F}_p & & \vec{F}_g & & \vec{F}_f & & \vec{F}_i \\ \downarrow & + & \downarrow & + & \downarrow & = & \downarrow \\ \text{Pressure} & & \text{Gravity} & & \text{Friction} & & \text{Inertia} \\ \text{force} & & \text{force} & & \text{force} & & \text{force or} \\ & & & & & & \text{Net force} \end{array}$$

- The dynamic similarity consider that

$$\frac{\vec{F}p_m}{\vec{F}p_p} = \frac{\vec{F}g_m}{\vec{F}g_p} = \frac{\vec{F}f_m}{\vec{F}f_p}$$

- In this flow through the sluice gate experiment, the force polygon at homologous points will have exactly the same shape if they are dynamically similar. This is possible, only if $Re_p = Re_m$ and $Fr_m = Fr_p$.

Example (Adopted from FM White's Fluid Mechanics)

- The pressure drop due to friction in a long circular pipe is a function of average velocity, density, viscosity, and pipe length and diameter.

$$\text{i.e. } \Delta P = f(V, \rho, \mu, L, D)$$

- Try to interpret how ΔP varies with V and use Pi-Theorem to rewrite the above function in dimensionless form.

Solution:

You are provided the information $\Delta P = f(V, \rho, \mu, L, D)$

- These are six basic variables $\Delta P, V, \rho, \mu, L, D$ (i.e. $n=6$)
- The basic dimensions are M, L, T (i.e. $k=3$)
- We expect $j = n - k = 6 - 3 = 3$ Π groups.

D (cm)	L (cm)	Q (m ³ /h)	ΔP (Pa)	ρ (kg/m ³)	μ (kg/ms)	V (m/s)
1.0	5.0	0.30	4680	680	$2.92 * 10^{-4}$	1.06
1.0	7.0	0.60	22300	680	$2.92 * 10^{-4}$	2.12
1.0	9.0	1.00	70800	680	$2.92 * 10^{-4}$	3.54
2.0	4.0	1.00	2080	998	0.0010	0.88
2.0	6.0	2.00	10500	998	0.0010	1.77
2.0	8.0	3.10	30400	998	0.0010	2.74
3.0	3.0	0.50	540	13550	$1.56 * 10^{-3}$	0.20
3.0	6.0	1.70	9600	13550	$1.56 * 10^{-3}$	0.67
3.0	4.0	1.00	2480	13550	$1.56 * 10^{-3}$	0.39

- As we want to see how ΔP varies with V , we are not going to keep it as repeating variable.

\therefore We will keep ρ, μ, D as repeating variable

$$\Pi_1 = \rho^a \mu^b D^c \Delta p \rightarrow M^0 L^0 T^0$$

$$\Pi_2 = \rho^d \mu^e D^f V \rightarrow M^0 L^0 T^0$$

$$\Pi_3 = \rho^g \mu^h D^i L \rightarrow M^0 L^0 T^0$$

Solving for exponents, you get:

$$\Pi_1 = \frac{\rho D^2 \Delta P}{\mu^2}, \Pi_2 = \frac{\rho V D}{\mu}, \Pi_3 = \frac{L}{D}$$

\therefore We will get a dimensionless expression

$$\frac{\rho D^2 \Delta P}{\mu^2} = f\left(\frac{\rho V D}{\mu}, \frac{L}{D}\right)$$

$$\Pi_1 = f(\Pi_2, \Pi_3)$$

As our objective is to find ΔP versus V ,

We have to plot Π_1 versus Π_2 with Π_3 as a parameter.

i.e. $\frac{L}{D} = 500$ for the first row of the data

$$\frac{\rho D^2 \Delta P}{\mu^2} = 3.73 \times 10^9$$

$$\frac{\rho V D}{\mu} = 24700$$

From second row of the data,

$$\frac{L}{D} = 700, \quad \frac{\rho D^2 \Delta P}{\mu^2} = 1.78 \times 10^{10}$$

$$\frac{\rho V D}{\mu} = 49370$$

Like this you evaluate for each row. Nine data points you will get.

- For same $\frac{L}{D}$ ratio, you will see ΔP is increasing linearly with L .